

Observed

N

Unobserved

p

W

Observed

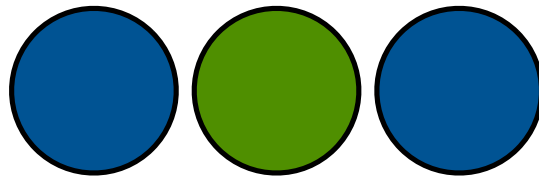


Definition of W

- Relative number of ways to see W , given N and p ?
- Goal: Mathematical function to answer this question.
- The answer is a *probability distribution*.

Definition of W

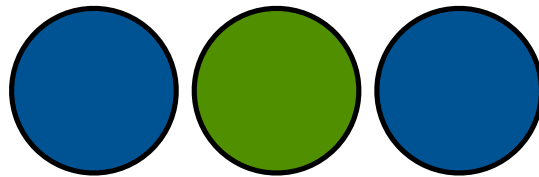
- Relative number of ways to see W , given N and p ?



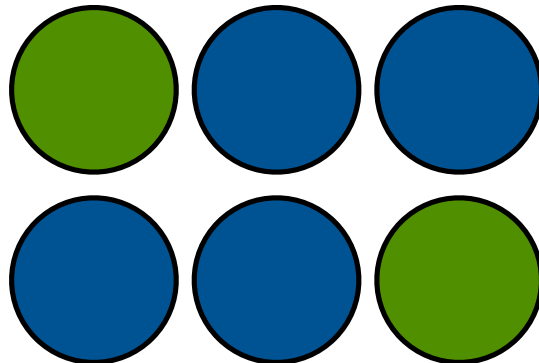
$$p \times (1-p) \times p = p^2(1-p)^1$$

Definition of W

- Relative number of ways to see W , given N and p ?

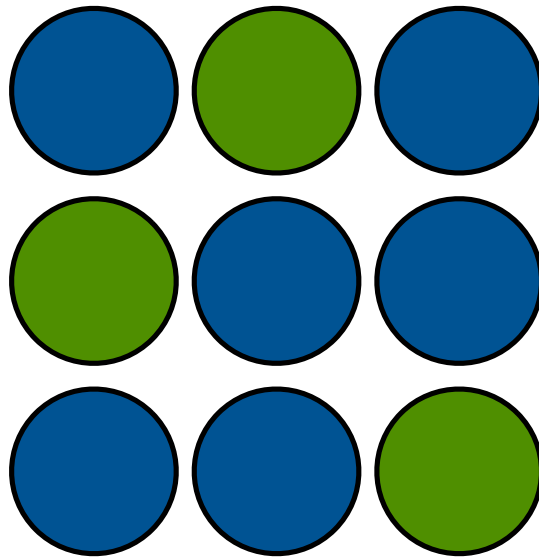


$$p \times (1-p) \times p = p^2(1-p)^1$$



Definition of W

- Relative number of ways to see W , given N and p ?



$$\Pr(2|3,p) = 3p^2(1-p)^1$$

W distribution (Likelihood)

$$\Pr(W|N, p) = \frac{N!}{W!(N-W)!} p^W (1-p)^{N-W}$$

number tosses (pointing to N)
count W (pointing to W)
probability W (pointing to p)

The count of W 's is distributed binomially, with probability p of a W on each toss and N tosses total.

W distribution (Likelihood)

$$\Pr(W|N, p) = \frac{N!}{W!(N - W)!} p^W (1 - p)^{N - W}$$

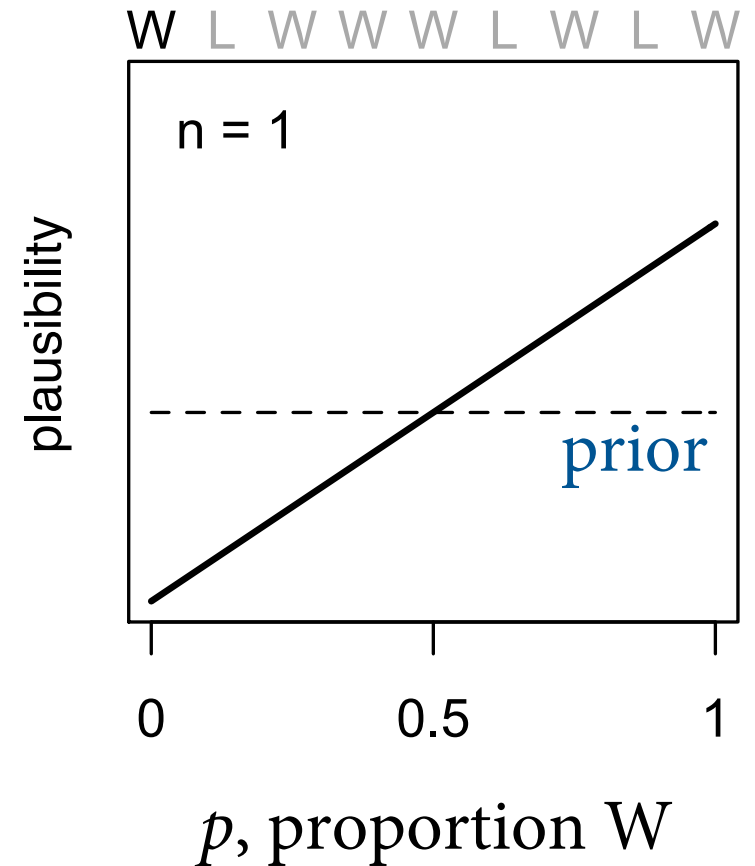
```
dbinom( 6 , size=9 , prob=0.5 )
```

```
[1] 0.1640625
```

R code
2.2

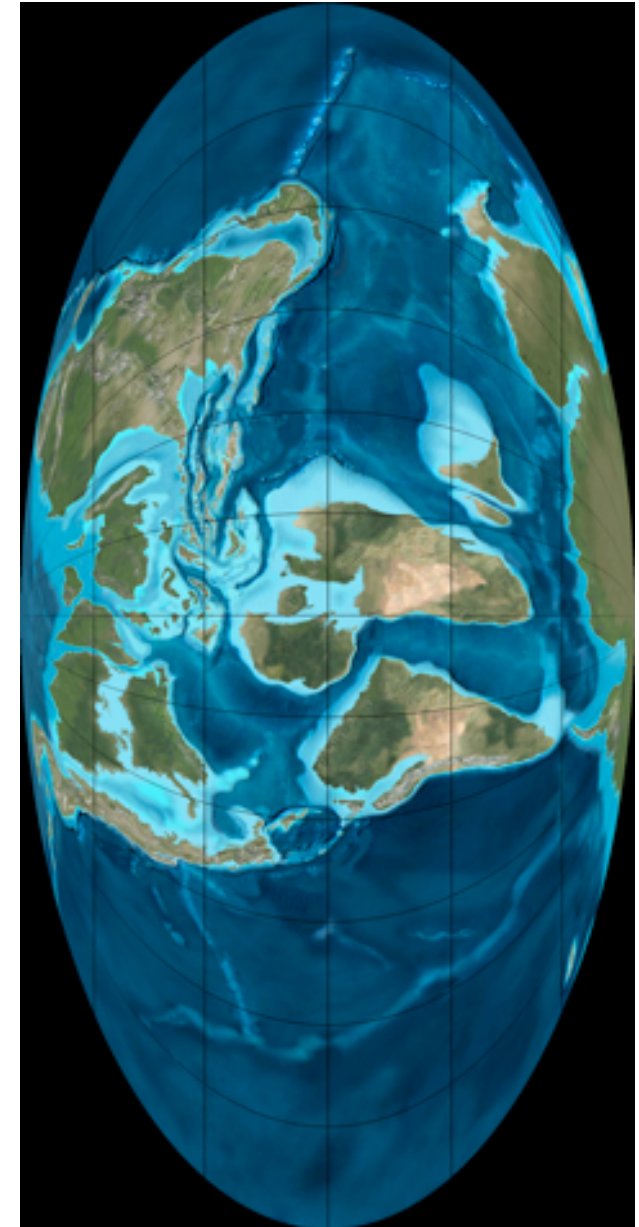
Prior probability p

- What the golem believes before the data arrive
- In this case, equal prior probability 0–1
- $\Pr(W)$ & $\Pr(p)$ define *prior predictive distribution*
- More on this later – it helps us build priors that make sense



Prior literature

- Huge literature on choice of prior
- Flat prior conventional & bad
 - Always know something (before data) that can improve inference
 - Are zero and one plausible values for p ? Is $p < 0.5$ as plausible as $p > 0.5$?
 - There is no “true” prior
 - Just need to do better than flat
- All above equally true of likelihood



Late Cretaceous (90Mya)

The Joint Model

$$W \sim \text{Binomial}(N, p)$$

$$p \sim \text{Uniform}(0, 1)$$

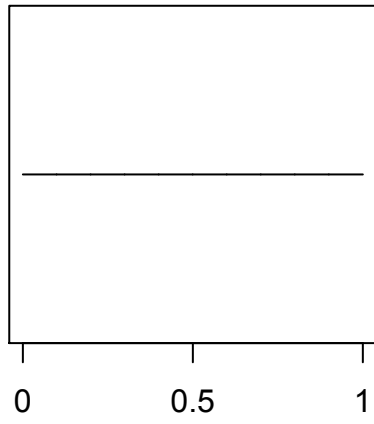
Posterior probability

- Bayesian “estimate” is always *posterior distribution over parameters*, $\Pr(\text{parameters}|\text{data})$
- Here: $\Pr(p|W,N)$
- Compute using *Bayes' theorem*:

$$\Pr(p|W, N) = \frac{\Pr(W|N, p) \Pr(p)}{\sum \Pr(W|N, p) \Pr(p) \text{ for all } p}$$

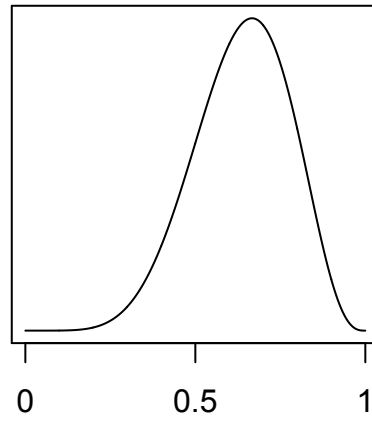
$$\text{Posterior} = \frac{(\text{Prob observed variables}) \times (\text{Prior})}{\text{Normalizing constant}}$$

prior



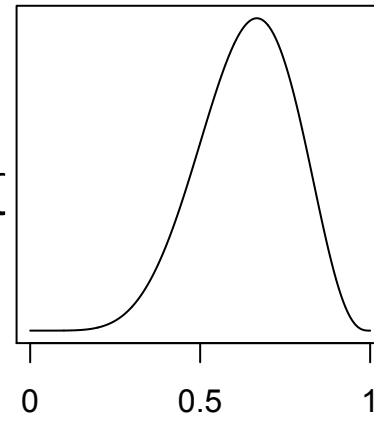
\times

likelihood



\propto

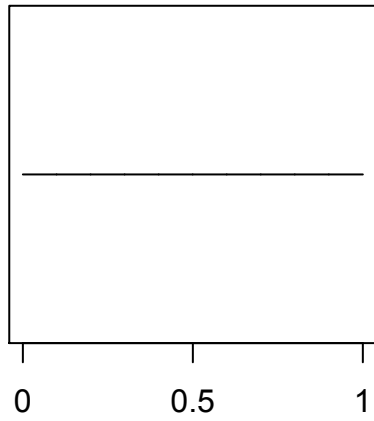
posterior



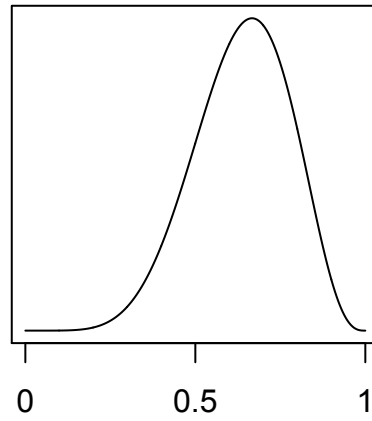
prior

likelihood

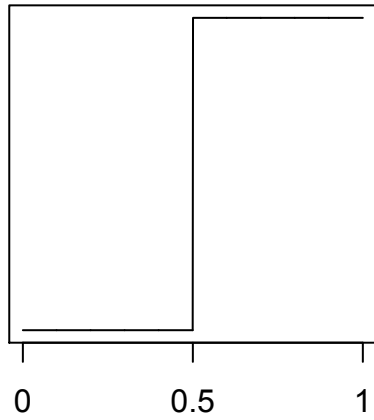
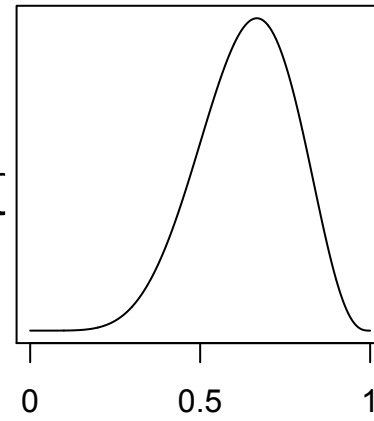
posterior



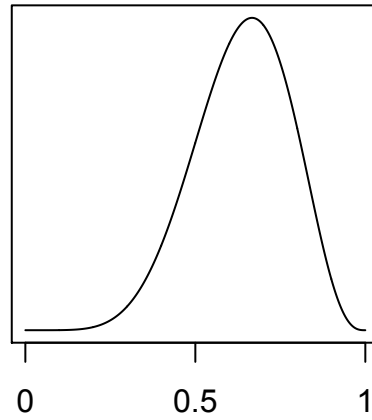
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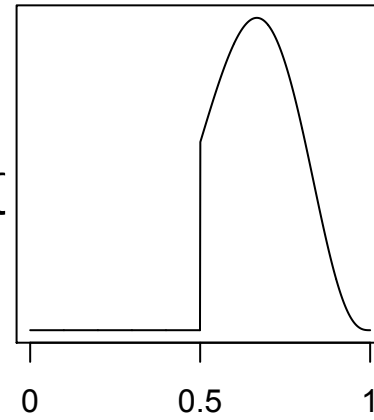
\propto



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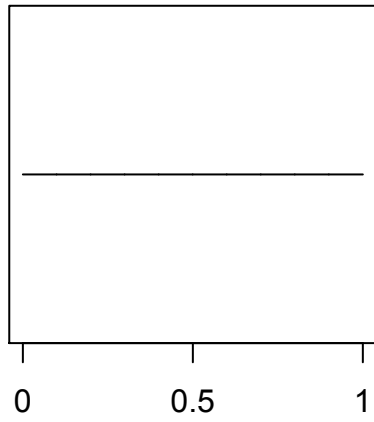
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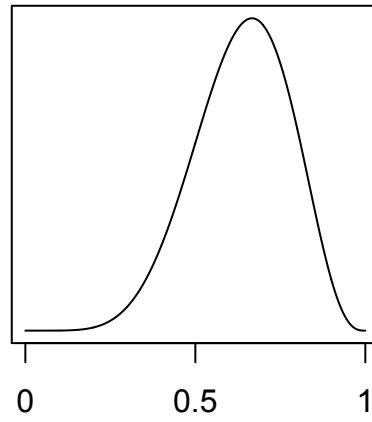
prior

likelihood

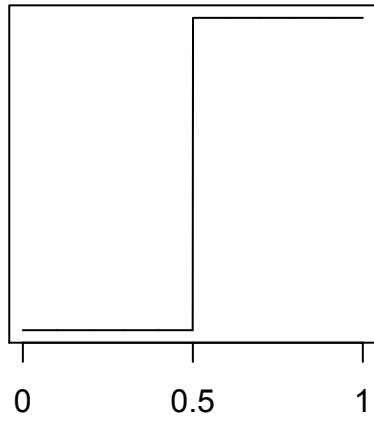
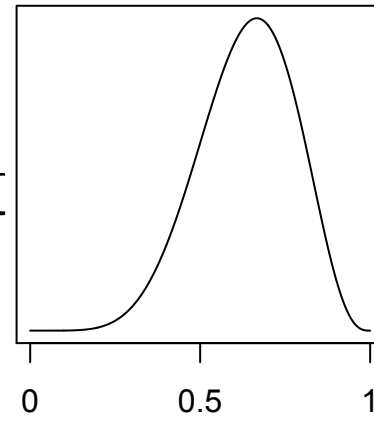
posterior



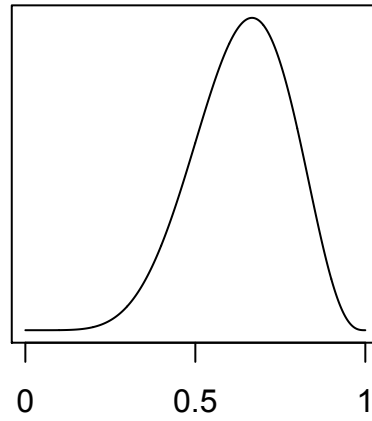
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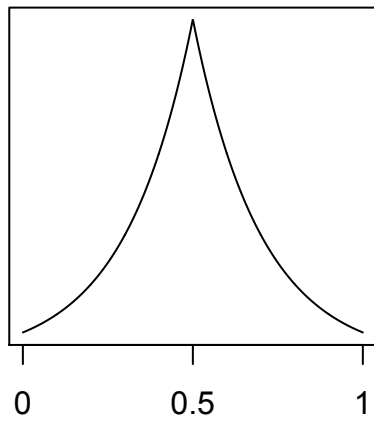
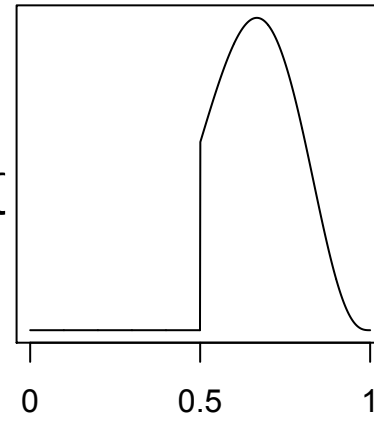
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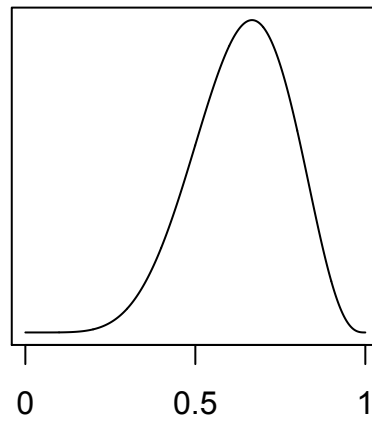
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\propto



\times



\propto

